

AL453 – UAV Control Short Course

1. *Kinematics and Dynamics*

- a. Kinematics
- b. Rigid Body Dynamics
- c. Coordinate Frames
- d. Air data

2. *Aircraft Forces and Moments*

- a. Forces and Moments
- b. Aerodynamics
- c. Trim Conditions

3. *Simplified Dynamics for Flight Control*

- a. Longitudinal Dynamics
- b. Lateral Dynamics

4. *Linear Quadratic Regulator*

- a. Steady State LQR
- b. Properties of LQR
- c. Example

5. *Servomechanism Design*

- a. Steady State Error
- b. Augmentation of Systems
- c. Internal Model Principle

6. *Frequency Domain Methods*

- a. Transfer Function Matrices
- b. Singular Value
Decomposition
- c. Nyquist Theorem

7. *Stability of MIMO Systems*

- a. Transfer Function Matrices
- b. Stability Robustness
- c. Singular Value Stability
Margins

8. *Robust Servomechanism LQR*

- a. Design Tools
- b. RSLQR Approach
- c. Application

9. *Projective Control*

- a. Output Feedback
- b. Application